

Article No.: 6SL3220-1YE18-0UF0

Client order no. : Order no. : Offer no. : Remarks :

Item no.:

Rated data

Input		
Number of phases	3 AC	
Line voltage	380 480 V +	10 % -20 %
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	6.90 A	5.80 A
, ,		
Rated current (HO)	5.50 A	4.60 A

Output

Overload capability

Low Overload (LO)	

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications	
Power factor λ	0.70 0.85
Offset factor cos φ	0.96
Efficiency η	0.97
Sound pressure level (1m)	55 dB
Power loss ₃₎	0.125 kW
Filter class (integrated)	Unfiltered
EMC category (with accessories)	without



Consignment no. : Project :

Ambient conditions		
Standard board coating type	Class 3C2, according to IEC 60721-3-3 2002	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.005 m³/s (0.177 ft³/s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-20 45 °C (-4 113 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-25 55 °C (-13 131 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Me	chanical data	
Degree of protection	IP20 / UL open type	
Size	FSA	
Net weight	3.2 kg (7.05 lb)	
Dimensions		
Width	73 mm (2.87 in)	
Height	232 mm (9.13 in)	
Depth	218 mm (8.58 in)	



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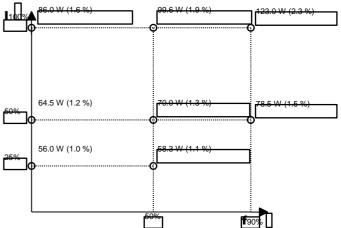
Input	ts / outputs	
Inputs / outputs Standard digital inputs		
Number		
Switching level: 0 → 1	6 11 V	
Switching level: 1 → 0	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number		
1Digital outputs		
Number as relay changeover contact 2Output (resistive load)	ot DC 30 V, 5.0 A	
Number as transistor	DC 30 V, 5.0 A	
0Analog / digital inputs		
Nimelean	O (Differential inner)	
Number	2 (Differential input)	
Resolution	10 bit	
Switching threshold as digital inpu		
0 → 1	4 V	
1 → 0	1.6 V	
Analog outputs		
Number	1 (Non-isolated output)	
PTC/ KTY interface		
1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy ±5 °C		
Closed-loop control techniques		
V/f linear / square-law / parameterizab l	le Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	

Yes

No

Communication

Con	Connections		
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	1.50 2.50 mm² (AWG 16 AWG 14)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	1.50 2.50 mm ² (AWG 16 AWG 14)		
DC link (for braking resistor)			
PE connection	On housing with M4 screw		
Max. motor cable length			
Shielded	150 m (492.13 ft)		
Unshielded	300 m (984.25 ft)		
Converter losses to IEC61800-9-2*			
Efficiency class	HE2		



36.2 %

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values

Comparison with the reference

converter (90% / 100%)

Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC

Encoderless torque control

Torque control, with encoder

Communication

PROFINET, EtherNet/IF

¹⁾ The output current and HP ratings are valid for the voltage range 440V-480V

³⁾ Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.